# Bar Graph Array Applications 

## Application Note 1007

## Introduction

The need for converting analog information into a visual display exists in many applications. Historically, the designer has had two possible solutions-the traditional panelmeter ordiscrete indicators aligned in an array. There are serious drawbacks with both solutions. Analog panel meters with inherent mechanical movements have been plagued with low tolerance for mechanical shock. Also, there is a strong customer demand for a more aesthetically pleasing display medium. Discrete indicators cause problems due to a high part count, difficult mechanical and optical alignment, as well as intensity and color variations across a display panel. Avago Technologies has solved many of these typical problems by introducing the HDSP-4820/-4830/-4840 series of 10-element LED bar graph arrays. The 10-element bar graph array series, available in standard red, high efficiency red, and yellow, offers the designer ultimate flexibility and ease of use in designing a display system.

This application note begins with a description of the manufacturing process used to construct the 10-element array. Next is a discussion of the package design and basic electrical configuration and how they affect designing with the bar graph array. This note also addresses mechanical information including pin spacing and wave soldering recommendations.

Two basic types of display interface techniques are thoroughly discussed. The first of these drive schemes is applicable in systems requiring display of analog signals in a bar graph format. The second major drive technique interfaces bar graph arrays in systems where the data is of a digital nature. Examples of microprocessor-controlled bar graph arrays are presented.

Summarized for the design engineer are tables of available integrated circuits for use with bar graph arrays. Finally, a list of recommended filters is included.

## Device Characteristics

The 10-element bar graph array devices are manufactured using the concept of "stretching" the light from an LED by diffusion and reflection as shown in Figure 1. The LED chips are mechanically supported and electrically connected by a lead frame. The plastic housing, called a "scrambler," contains reflective cavities which act as light pipes. These cavities are filled with a diffusant epoxy to provide uniform illumination at the emitting surface.


Figure 1. 10-element Bar Graph (Cutaway)

All bar graph arrays are manufactured in standard DIP packages with leads on 2.54 mm ( 0.100 inch) centers with a row-to-row spacing of 7.6 mm ( 0.300 inch). As shown in the device schematic in Figure 2, each LED anode and cathode is present on external pins for ease of use.

Each of the 10 elements within the device is matched for luminous intensity. The benefit of this matching is that users of a single 10-element array need not worry about element-to-element matching within the package. The average luminous intensity for the device is coded by a letter on the side of the package. In applications requiring two or more bar graph arrays end stacked, the user merely chooses devices from a single light intensity category to provide uniform brightness across the display panel.

Color uniformity of the bar graph arrays is an important consideration. The standard red and high efficiency red displays have inherent color uniformity and need not be categorized. However, the eye is more sensitive to color differences in the yellow region. Therefore, the yellow bar graph arrays are categorized by dominant wavelength. These categories are coded by a number on the side of the package. The user should choose units from a single color category to achieve a display panel with optimal color uniformity.

The bar graph arrays have a neutral gray top surface and untinted segments to ensure maximum color difference between on and off segments. To maximize contrast enhancement, specially developed filters should be used in conjunction with the bar graph arrays. A list of recommended filters is contained in Table I.


Figure 2. 10-Element Bar Graph Array Schematic

The bar graph arrays offer substantial improvement over discrete devices in the area of mechanical alignment. Because the ten light emitting cavities are molded in a single package, element-to-element consistency as well as mechanical and optical alignment are vastly improved. The package also has a unique interlocking mechanism that eases alignment in applications requiring arrays to be end stacked.

If the bar graph arrays are to be wave soldered, Sn60 or Sn63 solder is recommended. The solder wave temperature should be no greater than $260^{\circ} \mathrm{C}$ with a maximum dwell time of 3 seconds. The devices have a 1 mm ( 0.040 inch) standoff which provides clearance above the printed circuit board to facilitate flux removal.

To optimize optical performance, specifically developed plastics are used in the bar graph arrays. These plastics restrict the solvents that may be used for cleaning. It is recommended that only mixtures of Freon (F113) and alcohol be used for vapor cleaning processes. The immersion time in the vapors should be less than two minutes. Some suggested vapor cleaning solvents are Freon TE, Genesolv DI-15 or DE-15, Arklone A or K. A $60^{\circ} \mathrm{C}\left(140^{\circ} \mathrm{F}\right)$ water cleaning process may also be used, which includes a neutralizer rinse (3\% ammonia solution or equivalent), a surfactant rinse ( $1 \%$ detergent solution or equivalent), a surfactant rinse ( $1 \%$ detergent solution or equivalent), a hot water rinse, and a thorough
air dry. Room temperature cleaning may be accomplished with Freon T-35 or T-P35, Ethanol, Isopropanol, or water with a mild detergent.

## Analog Input Interface Techniques

 Many applications for bar graph arrays are in systems where the analog signal needs to be displayed with little or no conditioning. Several analog input IC decoders are available from different manufacturers and are listed in Table II. Although these decoders differ somewhat by manufacturer, the principle upon which they all operate is the same. A block diagram of a typical 5-element analog input bar graph decoder is shown in Figure 3. Within each IC is a reference voltage network and a set of comparators to detect the level of the analog input signal. When the input signal is greater than the reference voltage for the first comparator, the first output is enabled. As the input signal is increased, subsequent outputs are also enabled. Some manufacturers have incorporated two types of input signal decoding. The first type of decoding turns on all LEDs with voltage thresholds below the analog input (standard bar graph). The second type of decoding turns on only one output at any given time. When the analog input lies within the active region of a particular comparator ( $\mathrm{V}_{\text {REF }} \leq \mathrm{V}_{\text {IN }}<\mathrm{V}_{\text {REF }}+1$ ), that output is enabled and all others are disabled. This is known as the position indicator mode. Since only one LED is on at any time in the position indicator mode, power dissipation is signifi-

Figure 3. Typical Analog Input Bar Graph Decoder
cantly reduced. Examples of both types of decoding are discussed in this section.

The circuit shown in Figure 4 uses the Texas Instruments TL480C and the HDSP-4820 to form a low cost audio system VU meter. The ten comparators combined with the voltage reference network within the TL480C detect the level of an analog input signal at the A input. Output Q1 is switched to a logic low at a typical input voltage of 203 millivolts. Due to the logarithmic scaling within the part, as the input signal is increased by 2 dB increments, the subsequent outputs are switched to logic low levels and the LEDs are illuminated. If the TL480C is set to display full scale when the analog input is at 2.0 volts, 0 dB to 18 dB can be displayed on the bar graph array.

The circuit shown in Figure 5 utilizes the National LM3914 and the HDSP4830 to form a flexible, ten-element bar graph. The LM3914 is a versatile decoder in that it can operate in two distinct modes. The state of

MODE (pin 9) determines the display format. When it is tied directly to Vcc (pin 3), full bar graph decoding occurs. But when MODE is tied to pin 11, the LM3914 operates in position indicator mode. This MODE pin can also be used to cascade additional LM3914s to form bar graphs of greater resolution.

The circuit in Figure 5 displays a 0 V to 5 V signal on the HDSP-4830 high efficiency red bar graph array. The full scale reading is determined by the adjustable voltage at the REF OUT node. The LM3914 forces a nominal 1.25 V constant voltage between REF OUT (pin 7) and REF ADJ (pin 8). In Figure 5 this voltage is applied across resistor R1. Since this voltage is constant, a constant current flows through R1 giving an output voltage REF OUT as calculated below.

The value of R1 also determines the LED current. Approximately ten times the current that flows from REF OUT (pin 7) is drawn by each lighted LED. The calculation of LED current is shown below.

Therefore, by choosing R1 for the desired LED brightness, and using the value of $\mathrm{I}_{\text {ADJ }}$ stated in the LM3914 data sheet ( $75 \mu$ A typical), R2 can be determined. By using a potentiometer for R2, the value of REF OUT can be adjusted to the precise level desired.


Figure 4. Audio VU Meter


Figure 5. 0 V - 5 V Bar Graph/Position Indicator Meter


Figure 6. Low Power 0V-5V Bar Graph Meter

The LED current in Figure 5 has been set nominally to 10 mA DC using the techniques described above. When operated in position indicator mode with $\mathrm{V}_{\mathrm{CC}}=6.8 \mathrm{~V}$, the power dissipation is approximately 110 mW . The worst case power dissipation when operated in bar mode (10-elements on) is approximately 720 mW .

If low power dissipation and full bar graph decoding is desired, the LM3914 can be operated as shown in Figure 6. The LM3914 is again operated in position indicator mode. However, the ten LEDs are driven in series from a +24 V power supply. The REF OUT voltage is adjusted so the bar graph reads +5 V full scale.

## Equations

$$
\begin{aligned}
& \text { REF OUT }=1.25 \mathrm{~V}(1+\mathrm{R} 2 / \mathrm{R} 1)+\mathrm{I}_{\mathrm{ADJ}}(\mathrm{R} 2) \\
& \mathrm{I}_{\mathrm{LED}}=(1.25 \mathrm{~V} / \mathrm{R} 1)(10)
\end{aligned}
$$

When $\mathrm{V}_{\text {IN }}$ lies between 0 V and +0.5 V , no LEDs are on. When $\mathrm{V}_{\text {IN }}$ lies between +0.5 V and +1.0 V , Output 1 is enabled and LED 1 is illuminated. Each time the input voltage increases 0.5 V , the 10 mA sink moves to the next output pin, illuminating an additional LED. When the input voltage is +5 V or more ( +35 V maximum), all ten LEDs are illuminated with the same 10 mA . To the observer, the bar graph appears to operate identically to the one in Figure 5 when in BAR mode. However, the worst case power dissipation has been reduced by approximately half-to 380 mW .
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## Digital Input Interface Techniques

Many applications for bar graph arrays are in digital systems. While the data being displayed may relate directly to an analog signal, it often will be converted to a digital format for processing. This conversion can be accomplished by a microprocessor and/or dedicated hardware. Several interface techniques that have been developed for displaying this digitized data in bar graph form are covered in this section. A list of digital input integrated circuits suitable for use as bar graph drivers is compiled in Table III.

Binary Coded Decimal (BCD) is one commonly used method for coding display data in digital systems. Figures 7 and 8 contain circuits designed for interfacing BCD systems to a ten-element bar graph. In each case a 1 -of-10 decoder (7442) is used to convert the BCD information to the display format. The circuit in Figure 7 drives the bar graph in position indicator mode. That is, only the one

LED corresponding to the BCD input is on at any one time. The circuit in Figure 8 has additional hardware to provide a true bar graph display. Therefore, when any output is decoded and turned on, that LED and all the LEDs below it are illuminated. The circuits in Figures 7 and 8 use the HDSP-4840 yellow bar graph with the forward current set nominally at 10 mA DC.

Figure 9 shows a 30 -element, DC driven bar graph array utilizing the National MM5450 LED Display Driver. The circuit uses three HDSP-4830 high efficiency red bar graphs end stacked to form the display portion of the circuit. The MM5450 is a serial in-parallel out shift register with 34 output pins that can sink up to 15 mA each. This current can be adjusted by an external potentiometer applied between $\mathrm{V}_{\mathrm{DD}}$ (pin 20) and Brightness Control (pin 19). Serial data transfer from the data source,
in this case the microprocessor, to the display driver is accomplished with the two signals, SERIAL DATA and CLOCK. By using a format of a leading " 1 " bit followed by 35 data bits, data transfer is allowed with a minimal hardware interface. The 35 data bits are latched after the 36th bit is complete. This provides non-multiplexed, direct drive to the bar graph array.

Figure 10 contains the software necessary to interface the MM5450 to the 6800 microprocessor. The serial display data is transferred from the microprocessor via bit 7 of the data bus. The data is clocked in each time the microprocessor writes to the MM5450. The clocking is accomplished through a combination of higher order addresses, R/W, VMA, and $\phi 2$.

The software first outputs a start bit to the MM5450. Next, the binary
number corresponding to the number of bar graph elements to be displayed is loaded from memory location BINARY. This value is subtracted from $34_{10}=22_{H}$, leaving the number of OFF elements to be clocked. These OFF bits are clocked first, followed immediately by the ON bits. Finally, the 36 th clock pulse is generated, and the bar graph is illuminated. This display will remain illuminated without the need for microprocessor interaction until the data needs changing.

The user should ensure that the correct number of clock pulses are always applied to the MM5450. If this condition is violated, the bar graph displays erroneous data until it is reset. Due to the lack of an external reset pin on the MM5450, the chip must then be turned off and subsequently repowered to reset and initialize correctly.


Figure 7. 1-of-10 Position Indicator


Figure 8. BCD to 10-Element Bar Graph Array


Figure 9. Serial Data Interface Between 6800 and 30-Element Bar Graph Array

|  | B000 |  | ASMB, A, L |  |  | NUMBER OF ELEMENTS ON ( $3010=1 \mathrm{E}_{\mathrm{H}}$ OR LESS $)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | DSPLAY | EQU | \$B000 |  |
| 0006 |  |  | BINARY | ORG | \$0006 |  |
| 0006 |  |  |  | RMB | \$1 |  |
| 0400 |  |  |  | ORG | \$0400 |  |
| 0400 | 86 | 80 |  | LDA A | I, \$80 |  |
| 0402 | B7 | B000 |  | STA A | E, DSPLY | OUTPUT START BIT |
| 0405 | D6 | 06 |  | LDA B | D, BINARY | GET BINARY |
| 0407 | 86 | 22 |  | LDA A | I, \$22 |  |
| 0409 | 10 |  |  | SBA |  | DETERMINE $\operatorname{NUMBER~OF~ZEROS~}$ |
| 040A | 81 | 00 | ZEROS | CMP A | I, \$0 | NO ZEROS THEN BRANCH, ELSE CONTINUE |
| 040C | 27 | 06 |  | BEQ | ONES |  |
| 040E | 7 F | B000 |  | CLR | E, DSPLY | OUTPUT ZER O |
| 0411 | 4 A |  |  | DEC A |  |  |
| 0412 | 20 | F6 |  | BRA | ZEROS | LOOP |
| 0414 | 86 | 80 | ONES | LDA A | I, \$80 | LOAD ONES |
| 0416 | C1 | 00 |  | CMP B | I, \$00 |  |
| 0418 | 27 | 07 |  | BEQ | QUIT | BRANCH IF DONE, ELSE CONTINUE |
| 041A | B7 | B000 |  | STA A | E, DSPLY | OUTPUT ONE |
| 041 D | 5A |  |  | DEC B |  |  |
| 041E | 7E | 0416 |  | JMP | ONES + 2 | LOOP |
| 0421 | 7 F | B000 | QUIT | CLR | E, DSPLY | FINAL CLOCK, DATA LATCHED |
|  |  |  |  | END |  |  |

Figure 10. Software to Interface 6800 to the Circuit in Figure 9

Figure 11 shows an 8080A microprocessor to bar graph interface utilizing the Intersil ICM7218A. This display driver has an $8 \times 8$ static RAM to store display data, sourcing and sinking drivers, and refresh timing for interfacing up to 64 LED elements to a microprocessor. However, the ICM7218A drives these elements
at $20 \mathrm{~mA} \mathrm{I}_{\text {PEAK/ELEMENT (MINIMUM) }}$ on a $12 \%$ duty factor which may result in an unacceptably low average current and brightness. For this reason, the eight digit drivers are paralleled in pairs in Figure 11. This results in a 30-element bar graph array operating at 20 mA IPEAK/SEGMENT (MINIMUM) with a duty factor of $24 \%$.


Figure 11. Parallel Data Interface Between 8080A and 30 Element Bar Graph Array

The software to interface the 8080A to the ICM7218A is shown in Figure 14. With the MODE input at a logic high, WRITE is pulsed low. This clocks a control word from the data bus to the ICM7218A. This control word is decoded as described in Figure 12. Inputs $\mathrm{ID}_{4}, \mathrm{ID}_{5}$, and $\mathrm{ID}_{7}$ are all logic highs which initialize the device into the proper mode of operation. This means that the next eight data words that are clocked into the ICM7218A will appear on the strobed outputs.

Memory location BINARY contains the number of elements in the bar graph that are to be illuminated. The software converts this information to bar graph form by rotating a 1 bit through the accumulator until BINARY decrements to zero. Since the logic is inverted for the $\overline{d . p}$. output, an exclusive OR mask has been used to complement this bit. Also, since the digit drivers have been

MODE $=1$
CONTROL WORD FORMAT


MODE $=0 \quad$ DATA WORD FORMAT


UNCODED SEGMENT INFORMATION
LOGIC 1 REPRESENTS AN ON SEGMENT FOR ALL INPUTS EXCEPT d.p., WHERE LOGIC O REPRESENTS AN ON d.p.

Figure 12. MODE and DATA Words for the ICM7218A
paired, two OUTPUT instructions are required for each byte decoded. The software is graphically depicted in Figure 13. When the ICM7218A has received nine words (control word and eight data words), the information is displayed on the bar graph.

This bar graph array will remain illuminated without the need for microprocessor interaction until the data needs changing.

EXAMPLE: BINARY $=21_{10}=\mathbf{1 5}_{H}$


| d.p. | a | $b$ | c | e | g | $f$ | d |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

ICM7218A RAM
Figure 13. Subroutine LOAD

| 001 C |  |  |  | DSPLY | EQU | 001 CH |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 002C |  |  |  | MODE | EQU | 002 CH |  |
| 0000 |  |  |  |  | ORG | 0 E 000 H |  |
| E000 | 01 |  |  | BINARY | DB | 1 | ;NUMBER OF ELEMENTS ON ( $30{ }_{10}=1 \mathrm{E}_{\mathrm{H}}$ OR LESS ) |
| E001 | F5 |  |  | LOAD | PUSH | PSW |  |
| E002 | C5 |  |  |  | PUSH | B |  |
| E003 | E5 |  |  |  | PUSH | H |  |
| E004 | 3 E | F0 |  |  | MVI | A, 0 FOH |  |
| E006 | D3 | 2 C |  |  | OUT | MODE | ;MODE IS ONE |
| E008 | D3 | 1C |  |  | OUT | DSPLY | ;CLOCK CONTROL WORD |
| E00A | 3E | 00 |  |  | MVI | A, 00H |  |
| E00C | D3 | 2C |  |  | out | MODE | ;MODE IS ZERO |
| E00E | 06 | 08 |  |  | MVI | B, 08 H | ;BIT COUNTER |
| E010 | 0 E | 04 |  |  | MVI | C, 04 H | ;BYTE COUNTER |
| E012 | 21 | 00 | E0 |  | LXI | H, BINARY | ;GET BINARY |
| E015 | 7 E |  |  |  | MOV | A, M |  |
| E016 | FE | 00 |  |  | CPI | 00 |  |
| E018 | CA | 33 | E0 |  | JZ | LOOP 1 | ;JUMP IF ZERO, ELSE CONTINUE |
| E01B | 3 E | 00 |  | CLEAR | MVI | A, 00 |  |
| E01D | 37 |  |  | SET | STC |  | ;SET CARRY |
| E01E | 17 |  |  |  | RAL |  | ;ROTATE ONE BIT |
| E01F | 35 |  |  |  | DCR | M |  |
| E020 | CA | 33 | E0 |  | JZ | LOOP 1 | ; JUMP IF ZERO, ELSE CONTINUE |
| E023 | 05 |  |  |  | DCR | B | ;DECREMENT BIT COUNTER |
| E024 | C2 | 1D | E0 |  | JNZ | SET | ;JUMP IF NOT ZERO, ELSE CONTINUE |
| E027 | EE | 80 |  |  | XRI | 80H | ;COMPLEMENT BIT 7 |
| E029 | D3 | 1C |  |  | OUT | DSPLY | ;CLOCK DISPLAY |
| E02B | D3 | 1 C |  |  | OUT | DSPLY | ;CLOCK DISPLAY |
| E02D | 0D |  |  |  | DCR | C | ; DECREMENT BYTE COUNTER |
| E02E | 06 | 08 |  |  | MVI | B, 08 H | ;RESET BIT COUNTER |
| E030 | C3 | 1B | E0 |  | JMP | CLEAR | ;START NEW BYTE |
| E033 | EE | 80 |  | LOOP 1 | XRI | 80H | ;COMPLEMENT BIT 7 |
| E035 | D3 | 1C |  |  | OU'T | DSPLY | ;CLOCK DISPLAY |
| E037 | D3 | 1C |  |  | OUT | DSPLY | ;CLOCK DISPLAY |
| E039 | 0D |  |  |  | DCR | C | ;DECREMENT BYTE COUNTER |
| E03A | CA | 42 | E0 |  | JZ | QUIT | ;JUMP IF ZERO, ELSE CONTINUE |
| E03D | 3E | 80 |  |  | MVI | A, 80H | ;ENSURE BIT 7 CORRECT |
| E03F | C3 | 35 | E0 |  | JMP | LOOP $1+2$ |  |
| E042 | E1 |  |  | QUIT | POP | H |  |
| E043 | C 1 |  |  |  | POP | B |  |
| E044 | F1 |  |  |  | POP | PSW |  |
| E045 | C9 |  |  |  | RET |  |  |
| E046 |  |  |  |  | END |  |  |

Figure 14. Software to Interface 8080A to the Circuits in Figure 11

## Table I. Filter Materials

| LED Color | Panelgraphic | SGL Homalite | 3M C0. | Glarecheq | Rohm and Haas | Schott | OCLI | Polaroid |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Standard <br> Red | Ruby Red 60 <br> Dark Red 63 <br> Purple 90 | H100-1600 <br> H100-1605 <br> H100-1804 <br> (Purple) | R6510 <br> P7710 | Spectrafilter 112 <br> Spectrafllter 118 | Plexiglass 2423 <br> Oroglass 2414 | RG-645 <br> RG-630 |  |  |
| High <br> Efficiency <br> Red | Scarlet Red 65 <br> Neutral <br> Gray 10 | H100-1670 | R6310 <br> N0220 <br> (Neut.Gray) | Spectrafilter 110 <br> Spectrafilter 105 <br> (Neutral Gray) |  | RG-610 | SunguardTM <br> (Neut.Gray) $)$ | HNCP10 <br> (Neut. Gray) |
| Yellow | Yellow 27 <br> Neutral <br> Gray 10 | H100-1720 | A5910 <br> N0220 <br> (Neut.Gray) | Spectrafilter 106 <br> Spectrafilter 105 <br> (Neutral Gray) |  |  | SunguardTM <br> (Neut.Gray) $)$ | HNCP10 <br> (Neut.Gray) |

Addresses for companies listed above:

Panelgraphic Corp., 10 Henderson Dr. West Caldwell, NJ 07006 (201) 227-1500

SGL Homalite, 11 Brookside Drive
Wilmington, DE 19804 (302) 652-3686
3M Company, Visual Products Division
3M Center, Bldg. 220-10W
St Paul, MN 55101 (612) 733-0128

Glarecheq, Chequers Engraving Ltd. 1-4 Christina Street
London EC2A P4A England (01)739-6964
Rohm and Haas, Independence Mall West Philadelphia, PA 19105 (215) 592-3000

Schott Optical Glass, Duryea, PA 13642 (717) 457-7485

Optical Coating Labs, Inc. (OCLI)
2789 Griffen Avenue
Santa Rosa,CA 95401 (707)545-6440
Polaroid Corporation, Polarizer Division 20 Ames Street, Cambridge,MA (617) 577-2000/3655

Table II. Analog Input Bar Graph Array Drivers

| Part Number | Vendor* | Drive Conditions | Scale | Elements | Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| UAA170 | Siemens | $\leq 50 \mathrm{~mA} \mathrm{DC}$ | External | 16 | Position indicator only, user sets scale |
| UAA180 | Siemens | $10 \mathrm{~mA} \mathrm{DC} \mathrm{(typ)}$ | External | 12 | User sets scale |
| TL489 | TI | $\leq 40 \mathrm{~mA} \mathrm{DC}$ | Linear | 5 | 200 mV increments |
| TL487 | TI | $\leq 40 \mathrm{~mA} \mathrm{DC}$ | Log | 5 | 3 dB increments |
| TL490 | TI | $\leq 40 \mathrm{~mA} \mathrm{DC}$ | Linear | 10 | $50-200 \mathrm{mV}$ adjustable increments |
| TL480 | TI | $\leq 40 \mathrm{~mA} \mathrm{DC}$ | Log | 10 | 2 dB increments |
| TL491 | TI | $\leq-25 \mathrm{~mA} \mathrm{DC}$ | Linear | 10 | 50-200 mV adjustable increments |
| TL481 | TI | $\leq-25 \mathrm{~mA} \mathrm{DC}$ | Log | 10 | 2 dB increments |
| LM3914 | National | $2 \leq 1 \leq 30 \mathrm{~mA} \mathrm{DC}$ | Linear | 10 | Position indicator/bar option |
| LM3915 | National | $2 \leq 1 \leq 30 \mathrm{~mA} \mathrm{DC}$ | Log | 10 | Position indicator/bar option |
| LM3916 | National | $2 \leq 1 \leq 30 \mathrm{~mA} \mathrm{DC}$ | Log | 10 | Position indicator/bar option |
| U237B | AEG-Tel. | 20 mA (typ) | Linear | 5 | 200 mV increments ( 200 mV - 1000 mV ) |
| U244B | AEG-Tel. | 20 mA (typ) | Linear | 5 | 180 mV increments ( 200 mV - 1000 mV with overlap) |
| U247B | AEG-Tel. | 20 mA (typ) | Linear | 5 | 200 mV increments ( 100 mV -900 mV) |
| U254B | AEG-Tel. | 20 mA (typ) | Linear | 5 | 100 mV increments ( 110 mV -900 mV with overlap) |
| U257B | AEG-Tel. | 20 mA (typ) | Log | 5 | -15 dB to +6 dB |
| U267B | AEG-Tel. | 20 mA (typ) | Log | 5 | -20 dB to +3 dB |
| XR-2277 | Exar | $\leq 18 \mathrm{~mA} \mathrm{DC}$ | Log | 12 | -30 dB to +6 dB , position indicator/bar option |
| XR-2278 | Exar | $\leq 18 \mathrm{mADC}$ | Log | 12 | -20 dB to +8 dB , position indicator/bar option |
| XR-2279 | Exar | $\leq 18 \mathrm{~mA} \mathrm{DC}$ | Log | 12 | 3 dB increments, position indicator/bar option |

*This is a partial list of vendors. Other suppliers may exist.

Table III. Digital Input Bar Graph Drlvers

| Part <br> Number | Vendor* | Drive <br> Conditions | Elements | Comments |
| :--- | :---: | :---: | :---: | :--- |
| MM74C911 | National | $100 \mathrm{~mA} \mathrm{pk}, 25 \%$ DF | 32 | Software decode, parallel interface |
| MM5450/51 | National | $\leq 15 \mathrm{~mA} \mathrm{DC}$ | $34 / 35$ | Software decode, serial interface |
| ICM7218A | Intersil | $20 \mathrm{~mA} \mathrm{pk}, 12 \%$ DF | 64 | Common Anode, software decode, parallel interface |
| 8243 | Signetics | 13 mA DC | 8 | n of 8 decoder |
| 7442 | Tl, <br> Fairchild, <br> et al. | 16 mA DC | 10 | 1 of 10 decoder |

